On the local null controllability of a cubic Ginzburg-Landau equation with dynamic boundary conditions

Nicolás Carreño, Alberto Mercado and Roberto Morales

Let $\Omega\subset\mathbb{R}^d$ $(d\geq 2)$ be a bounded domain with boundary $\Gamma:=\partial\Omega$ of class C^2 . For T>0, we define the sets $Q:=\Omega\times(0,T), \Sigma:=\Gamma\times(0,T)$ and for any subset $\omega\subset\Omega$, we write $Q_\omega:=\omega\times(0,T)$.

For a, b > 0 and $\alpha \in \mathbb{R}$, we define the linear operators

$$L(u) := \partial_t u - a(1 + \alpha i) \Delta u$$

$$L_{\Gamma}(u, u_{\Gamma}) := \partial_t u_{\Gamma} + a(1 + \alpha i) \partial_{\nu} u - b(1 + \alpha i) \Delta_{\Gamma} u_{\Gamma}$$

Moreover, for $c, \gamma \in \mathbb{R}$ we put $f(w) := c(1 + \gamma i)|w|^2 w_{\Gamma}$. Then, we consider the following system

$$(1) \qquad \begin{cases} L(u) + f(u) = \mathbb{1}_{\omega}h & \text{in } Q, \\ L_{\Gamma}(u, u_{\Gamma}) + f(u_{\Gamma}) = 0 & \text{on } \Sigma, \\ u\big|_{\Gamma} = u_{\Gamma} & \text{on } \Sigma, \\ (u(\cdot, 0), u_{\Gamma}(\cdot, 0)) = (u_0, u_{\Gamma, 0}) & \text{in } \Omega \times \Gamma. \end{cases}$$

The control h acts only on the first equation. This means that the second equation (i.e., the general dynamic boundary condition) is controlled by the side condition $u|_{\Gamma} = u_{\Gamma}$.

Let us define the spaces

$$\begin{split} \mathbb{L}^2 := & L^2(\Omega) \times L^2(\Gamma), \\ \mathbb{H}^k := & \{(y, y_\Gamma) \in H^k(\Omega) \times H^k(\Gamma) \, : \, y\big|_{\Gamma} = y_\Gamma \} \end{split}$$

It is not difficult to see that, under a smallness condition on

both the initial data and the control, a unique solution of (1) exists.

Our main result is the following

THEOREM 1 Suppose that d=2 or d=3 and $\omega \in \Omega$. Then, the system (1) is **locally null controllable at every time** T in \mathbb{H}^1 , i.e., there exists $\delta>0$ such that, for every $(u_0,u_{\Gamma,0})\in \mathbb{H}^1$ verifying

$$||(u_0, u_{\Gamma,0})||_{\mathbb{H}^1} \le \delta,$$

there exists a control $h \in L^2(\omega \times (0,T))$ such that the solution (u,u_Γ) of (1) satisfies

$$u(\cdot,T)=0$$
 in Ω , $u_{\Gamma}(\cdot,T)=0$ on Γ .

Acknowledgements

This project has received funding from the European Research Council (ERC) under the European Union's Horizon 2030 research and innovation programme (grant agreement NO: 101096251-CoDeFeL)

References

 N. Carreño, Mercado, A., & R. Morales. Local null controllability of a cubic Ginzburg-Landau equation with dynamic boundary conditions (To appear in Journal of Evolution Equations) https://arxiv.org/abs/2301.03429

^{*}Departamento de Matemática, Universidad Técnica Federico Santa María, Casilla 110-V, Valparaíso, Chile Email: nicolas.carrenog@usm.cl, alberto.mercado@usm.cl

[†]Chair of Computational Mathematics, DeustoTech, University of Deusto, Avenida de las Universidades 24, 48007 Bilbao, Basque Country, Spain.